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## Cold Plasma Dispersion relation

Let us go back to a single particle and see how it behaves in a high frequency electric field. We will use the force equation and Maxwell's equations. The high frequency field will be that of a wave in the plasma.

The high frequency field is  $\vec{E}(t) = \vec{E}_0 e^{i\omega t}$ . The frequency can be as

high as the cyclotron frequency. The force law is

 $\frac{d\mathbf{v}}{d\mathbf{t}} = \frac{q}{m} \left( \vec{E}_0 e^{i\omega t} + \vec{\mathbf{v}} \times \vec{B} \right).$  Let  $\vec{\mathbf{v}} = \vec{\mathbf{v}}_c + \vec{\mathbf{v}}_E e^{i\omega t}$ , where  $\mathbf{v}_c$  does not depend on  $\omega$ .

The force law gives us:

$$\frac{d\vec{v}_{c}}{dt} + i\omega\vec{v}_{E}e^{i\omega t} = \frac{q}{m}\left(\vec{E}_{0}e^{i\omega t} + \vec{v}_{c}\times\vec{B} + \vec{v}_{E}\times\vec{B}e^{i\omega t}\right).$$
 One set of terms has a  $\omega$  in

front of them all and an  $e^{i\omega t}$  dependance, the other does not; in fact we have 2 equations:

 $(I) \quad \frac{d\vec{v}_{c}}{dt} + = \frac{q}{m} (\vec{v}_{c} \times \vec{B})$  $i\omega \vec{v}_{E} e^{i\omega t} = \frac{q}{m} \vec{E}_{0} e^{i\omega t} + \frac{q}{m} \vec{v}_{E} \times \vec{B} e^{i\omega t}$  The first is the usual cyclotron motion

equation, we know the answer( see appendix I) . The second may be re-written as

(II)  $(i\omega + \frac{q}{m}\vec{B}\times)\vec{v}_{E} = \frac{q}{m}\vec{E}$ . Now multiply equation II by the operator  $(i\omega - \frac{q}{m}\vec{B}\times)$   $\left((i\omega - \frac{q}{m}\vec{B}\times)\right)(i\omega + \frac{q}{m}\vec{B}\times)\vec{v}_{E} = \frac{q}{m}(i\omega - \frac{q}{m}\vec{B}\times)\vec{E}$ . Let us now see what the left hand side is  $\left((i\omega - \frac{q}{m}\vec{B}\times)\right)(i\omega + \frac{q}{m}\vec{B}\times)\vec{v}_{E} = -\omega^{2}\vec{v}_{E} - \frac{q^{2}}{m^{2}}\vec{B}\times(\vec{B}\times\vec{v}_{E})$  $= -\omega^{2}\vec{v}_{E} - \frac{q^{2}}{m^{2}}(\vec{B}\cdot\vec{v}_{E})\vec{B} + \frac{q^{2}}{m^{2}}B^{2}\vec{v}_{E}$  Equating both sides

$$-\omega^2 \vec{\mathbf{v}}_{\rm E} - \frac{q^2}{m^2} \left( \vec{B} \cdot \vec{\mathbf{v}}_{\rm E} \right) \vec{B} + \frac{q^2}{m^2} B^2 \vec{\mathbf{v}}_{\rm E} = \frac{q}{m} (i\omega - \frac{q}{m} \vec{B} \times) \vec{E} \quad \text{This may be written as}$$
$$\left( \omega_c^2 - \omega^2 \right) \vec{\mathbf{v}}_{\rm E} - \frac{q^2}{m^2} \left( \vec{B} \cdot \vec{\mathbf{v}}_{\rm E} \right) \vec{B} = \frac{q}{m} (i\omega - \frac{q}{m} \vec{B} \times) \vec{E} \quad ; \frac{q^2 B^2}{m^2} = \omega_c^2$$

The next step is to break the velocity into components perpendicular and parallel to the magnetic field. First for the parallel case. The parallel case  $\vec{B} \cdot \vec{v}_{E\parallel} = B v_{E_{\perp}}$ 

$$\vec{\mathbf{v}}_{\rm E} = \vec{\mathbf{v}}_{\rm E\parallel} + \vec{\mathbf{v}}_{\rm E\perp}$$
$$\left(\omega_c^2 - \omega^2\right) \vec{\mathbf{v}}_{\rm E\parallel} - \frac{q^2 B^2}{m^2} \vec{\mathbf{v}}_{\rm E\parallel} = i\omega \frac{q}{m} \vec{E}_{\parallel} , \vec{B} \times \vec{E} \text{ is } \perp \text{ to } \mathbf{B}$$

(III)  $\vec{v}_{E\parallel} = -i \frac{q}{\omega m} \vec{E}_{\parallel}$  The parallel component of v oscillates as if B was

not there but the oscillation is out of phase by 90 degrees ( $i = e^{\frac{i\pi}{2}}$ ). For the perpendicular component

$$\left(\omega_c^2 - \omega^2\right) \vec{v}_{E\perp} = \frac{q}{m} (i\omega - \vec{\omega}_c \times) \vec{E}_{\perp} , \vec{\omega}_c = \frac{q\vec{B}}{m}$$

$$(IV) \quad \vec{v}_{E\perp} = \frac{q}{m} \frac{(i\omega - \vec{\omega}_c \times) \vec{E}_{\perp}}{\left(\omega_c^2 - \omega^2\right)}$$
Note this has a resonance at the cyclotron

frequency. This is an operator equation of the form  $\vec{v}_{\perp} = \vec{A}\vec{E}_{\perp}$  where A is a complex operator, which could be a tensor. Now let us further break down the perpendicular velocity and electric field (which is that of the wave) into two components each rotating around the magnetic field in opposite directions.

 $\vec{v}_{\perp} = \vec{v}_{L} + \vec{v}_{R}$   $\vec{E}_{\perp} = \vec{E}_{L} + \vec{E}_{R}$ . Using (IV) as a guide

(V) 
$$\vec{E}_L = \frac{1}{2} \left[ \vec{E}_\perp + \frac{(i\vec{\omega}_c \times)\vec{E}_\perp}{(\omega_c)} \right]; \vec{E}_R = \frac{1}{2} \left[ \vec{E}_\perp - \frac{(i\vec{\omega}_c \times)\vec{E}_\perp}{(\omega_c)} \right]; \vec{E}_\perp \Longrightarrow \vec{E}_\perp e^{i\omega t}.$$
 Let us now

assume the magnetic field is constant and is in the z direction.

$$\vec{E}_{L} = \frac{1}{2} \Big[ E_{\perp} e^{i\omega t} \hat{r} + iE_{\perp} e^{i\omega t} \hat{\theta} \Big] ; \vec{E}_{R} = \frac{1}{2} \Big[ \Big[ E_{\perp} e^{i\omega t} \hat{r} - iE_{\perp} e^{i\omega t} \hat{\theta} \Big] \Big] ; \vec{B} = B_{0} \hat{k}$$
  

$$\operatorname{Re}(\vec{E}_{L}) = \frac{1}{2} \Big[ E_{\perp} \cos(\omega t) \hat{r} + \operatorname{Re}(i(\cos(\omega t) + i\sin(\omega t))) E_{\perp} \hat{\theta} \Big] = \frac{1}{2} E_{\perp} \cos(\omega t) \hat{r} - \frac{1}{2} E_{\perp} \sin(\omega t) E_{\perp} \hat{\theta}$$

This is an electric field vector that rotates clockwise around the magnetic field. This is the same direction that an ion will take so the  $E_L$  field can resonate with the ion gyro motion.

The  $E_R$  field will resonant with the electrons as it will rotate in the counterclockwise direction. If we re-write the electric field in the perpendicular direction for ion motion as:

$$\vec{E}_{\perp} = E_x \hat{i} + E_y \hat{j} \quad \vec{\omega}_{\rm C} = \omega_C \hat{k}$$
  
for  $E_{\rm L}$ ,  $E_{\rm L} = \frac{1}{2} \left( E_x \hat{i} + E_y \hat{j} \right) + \frac{1}{2} i \hat{k} \times \left[ E_x \hat{i} + E_y \hat{j} \right] = \frac{1}{2} \left( E_x - i E_y \right) \times \left[ \hat{i} + i \hat{j} \right]$ 

the time dependence is still inside E in the above. If we put the time dependence back  $\operatorname{Re}\left[\hat{i} + i\hat{j}\right]e^{i\omega t} = \cos(\omega t)\hat{i} - \sin(\omega t)\hat{j}$ 

which is a unit vector spinning in the L direction. Now substitute the rotating vectors into equation (IV) first for  $E_L$  then for  $E_R$ .

$$(i\omega - \vec{\omega}_{c} \times)\vec{E}_{L} = \frac{1}{2} (i\omega - \vec{\omega}_{c} \times) \left[\vec{E}_{\perp} + \frac{(i\vec{\omega}_{c} \times)\vec{E}_{\perp}}{(\omega_{c})}\right]$$
$$= \frac{1}{2} \{i\omega\vec{E}_{\perp} - \vec{\omega}_{c} \times \vec{E}_{\perp} - \frac{\omega(\vec{\omega}_{c} \times)\vec{E}_{\perp}}{(\omega_{c})} - \frac{(i\vec{\omega}_{c} \times)(\vec{\omega}_{c} \times \vec{E}_{\perp})}{(\omega_{c})}\}$$
$$= \frac{1}{2} i \left\{ (\omega + \omega_{c}) \left[\vec{E}_{\perp} + \frac{i\vec{\omega}_{c} \times \vec{E}_{\perp}}{\omega_{c}}\right] \right\} = i(\omega + \omega_{c})\vec{E}_{L} \text{ (note } \vec{E}_{\perp} \cdot \vec{\omega}_{c} = 0)$$

Then the operator equation (IV) is

(V)  
$$\vec{v}_{L} = \frac{qi}{m} \frac{(\omega + \omega_{c})\vec{E}_{L}}{(\omega_{c}^{2} - \omega^{2})} = \frac{qi}{m} \frac{\vec{E}_{L}}{(\omega_{c} - \omega)}$$
$$\vec{v}_{R} = \frac{-qi}{m} \frac{\vec{E}_{L}}{(\omega_{c} + \omega)}$$

This may be written as a tensor for the rotating electric field in the frame of the rotating particle

(VI) 
$$\vec{\mathbf{v}} = \begin{bmatrix} \mathbf{v}_{\mathrm{L}} \\ \mathbf{v}_{\mathrm{R}} \\ \mathbf{v}_{\mathrm{H}} \end{bmatrix} = \vec{\mathbf{v}}\vec{E} = \frac{iq}{m} \begin{bmatrix} \frac{1}{\omega_{c} - \omega} & 0 & 0 \\ 0 & \frac{-1}{\omega_{c} + \omega} & 0 \\ 0 & 0 & \frac{-1}{\omega} \end{bmatrix} \begin{bmatrix} \mathbf{E}_{\mathrm{L}} \\ \mathbf{E}_{\mathrm{R}} \\ \mathbf{E}_{\mathrm{H}} \end{bmatrix}$$

Note that in this rotating frame the mobility tensor is a diagonal. Now using the definitions for  $E_R$ ,  $E_L$  etc in the notes we can transform back into the xyz system (see appendix A) to get:

(VII) 
$$\begin{bmatrix} \mathbf{v}_{x} \\ \mathbf{v}_{y} \\ \mathbf{v}_{z} \end{bmatrix} = \frac{q}{m} \begin{bmatrix} \frac{i\omega}{\omega_{c}^{2} - \omega^{2}} & \frac{\omega_{c}}{\omega_{c}^{2} - \omega^{2}} & 0 \\ \frac{-\omega_{c}}{\omega_{c}^{2} - \omega^{2}} & \frac{i\omega}{\omega_{c}^{2} - \omega^{2}} & 0 \\ 0 & 0 & -\frac{i}{\omega} \end{bmatrix} \begin{bmatrix} E_{x} \\ E_{y} \\ E_{z} \end{bmatrix}$$

## Appendix A

How do we go from rotating coordinates back to rectangular ones? In the notes:

(A1) 
$$\vec{E}_L = \frac{1}{2} \left( E_x - iE_y \right) \left( \hat{i} + i\hat{j} \right)$$

What about the other component?

$$(A2) \quad \vec{E}_{R} = \frac{1}{2} \left( E_{\perp} - \frac{i\vec{\omega}_{c} \times \vec{E}_{\perp}}{\omega_{c}} \right), \text{ substitute for } E_{\perp} \text{ in this}$$

$$\vec{E}_{R} = \frac{1}{2} \left( E_{x}\hat{i} + E_{y}\hat{j} - \frac{i\vec{\omega}_{c} \times \left(E_{x}\hat{i} + E_{y}\hat{j}\right)}{\omega_{c}} \right) = \frac{1}{2} \left( E_{x}\hat{i} + E_{y}\hat{j} - \frac{i\omega_{c}\hat{k} \times \left(E_{x}\hat{i} + E_{y}\hat{j}\right)}{\omega_{c}} \right)$$

$$\vec{E}_{r} = \frac{1}{2} \left( E_{x}\hat{i} + E_{y}\hat{j} - \frac{i\omega_{c}\left(E_{x}\hat{j} - E_{y}\hat{i}\right)}{\omega_{c}} \right) = \frac{1}{2} \left( E_{x}\left[\hat{i} - i\hat{j}\right] + E_{y}\left[\hat{j} + i\hat{i}\right] \right)$$

$$(A3) \quad \vec{E}_{r} = \frac{1}{2} \left( E_{x} + iE_{y}\right) \left[\hat{i} - i\hat{j}\right]$$

Now with (A1) and (A3) we have to find  $E_x$ ,  $E_y$  in terms of the left and right components. The velocities have the same form as the fields

(A4)  
$$\vec{\mathbf{v}}_{L} = \frac{1}{2} (\mathbf{v}_{x} - i\mathbf{v}_{y}) [\hat{i} + i\hat{j}]$$
$$\vec{\mathbf{v}}_{R} = \frac{1}{2} (\mathbf{v}_{x} + i\mathbf{v}_{y}) [\hat{i} - i\hat{j}]$$

But 
$$\vec{v}_L = \frac{iq}{m} \frac{1}{(\omega_c - \omega)} \vec{E}_L$$

Therefore by substitution:

$$(\mathbf{v}_{x} - i\mathbf{v}_{y}) = \frac{iq}{m} \frac{1}{(\omega_{c} - \omega)} \frac{1}{2} (E_{x} - iE_{y})$$

$$(A5) \quad \mathbf{v}_{y} = -\frac{q}{m} \frac{1}{(\omega_{c} - \omega)} (E_{x} - iE_{y}) - i\mathbf{v}_{x}$$

Next use the definition of  $v_{\mbox{\scriptsize r}}$ 

$$\vec{\mathbf{v}}_{R} = -\frac{iq}{m} \frac{1}{\left(\boldsymbol{\omega}_{c} + \boldsymbol{\omega}\right)} \vec{E}_{R}$$

and using the definitions again

$$\frac{1}{2} \left( \mathbf{v}_{x} + i\mathbf{v}_{y} \right) = -\frac{iq}{m} \frac{1}{\left(\omega_{c} + \omega\right)} \frac{1}{2} \left( E_{x} + iE_{y} \right)$$
$$i\mathbf{v}_{y} = -\frac{iq}{m} \frac{1}{\left(\omega_{c} + \omega\right)} \left( E_{x} + iE_{y} \right) - \mathbf{v}_{x}$$
$$\mathbf{v}_{y} = -\frac{q}{m} \frac{1}{\left(\omega_{c} + \omega\right)} \left( E_{x} + iE_{y} \right) + i\mathbf{v}_{x}$$
(A6)

Next equate the two (A5) and (A6)

$$-\frac{q}{m}\frac{1}{(\omega_{c}+\omega)}\left(E_{x}+iE_{y}\right)+iv_{x}=-\frac{q}{m}\frac{1}{(\omega_{c}-\omega)}\left(E_{x}-iE_{y}\right)-iv_{x}$$

$$2iv_{x}=-\frac{q}{m}\frac{1}{(\omega_{c}-\omega)}\left(E_{x}-iE_{y}\right)+\frac{q}{m}\frac{1}{(\omega_{c}+\omega)}\left(E_{x}+iE_{y}\right)$$

$$2iv_{x}=\frac{q}{m}\left[-\frac{1}{(\omega_{c}-\omega)}+\frac{1}{(\omega_{c}+\omega)}\right]E_{x}+iE_{y}\frac{q}{m}\left[\frac{1}{(\omega_{c}+\omega)}+\frac{1}{(\omega_{c}-\omega)}\right]$$

$$v_{x}=\frac{q}{m}\left[\frac{i\omega}{(\omega_{c}^{2}-\omega^{2})}\right]E_{x}+\frac{q}{m}\left[\frac{\omega_{c}}{(\omega_{c}^{2}-\omega^{2})}\right]E_{y}$$

Do the same thing for the y component to get

$$\mathbf{v}_{y} = \frac{q}{m} \left[ \frac{-\boldsymbol{\omega}_{c}}{\left(\boldsymbol{\omega}_{c}^{2} - \boldsymbol{\omega}^{2}\right)} \right] E_{x} + \frac{q}{m} \left[ \frac{i\boldsymbol{\omega}}{\left(\boldsymbol{\omega}_{c}^{2} - \boldsymbol{\omega}^{2}\right)} \right] E_{y}$$

From before the z component was simple

$$\mathbf{v}_{\parallel} = \mathbf{v}_z = -\frac{iq}{m\omega}E_z$$

We can put this into matrix form

$$\begin{pmatrix} \mathbf{v}_{x} \\ \mathbf{v}_{y} \\ \mathbf{v}_{z} \end{pmatrix} = \frac{q}{m} \begin{bmatrix} \frac{i\omega}{(\omega_{c}^{2} - \omega^{2})} & \frac{\omega_{c}}{(\omega_{c}^{2} - \omega^{2})} & 0 \\ \frac{-\omega_{c}}{(\omega_{c}^{2} - \omega^{2})} & \frac{i\omega}{(\omega_{c}^{2} - \omega^{2})} & 0 \\ 0 & 0 & \frac{i}{\omega} \end{bmatrix} \begin{pmatrix} E_{x} \\ E_{y} \\ E_{z} \end{pmatrix}$$